

The Effect of Short-term Muscle Vibration on Knee Joint Torque and Muscle Firing Patterns during a Maximal Voluntary Isometric Contraction

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Objective: To investigate the effect of short-term vibration frequencies on muscle force generation capabilities.

Method: Six healthy participants were recruited for this study and only their dominant leg was tested. The subjects were tested under five conditions of vibration frequencies with constant amplitude: 0 Hz (no vibration), 30 Hz, 60 Hz, and 90 Hz, and the vibration amplitude was 10 mm for all frequency conditions. The vibration was applied to the rectus femoris (RF). The subjects were then instructed to maintain a steady-state isometric knee joint torque (100 Nm) for the first 6 s. After the steady-state torque production, the subjects were required to produce isometric knee joint torque by leg extension as hard as possible with a start signal within the next 3 s. The vibration was applied for ~4 s starting from 1 s before initiation of the change in the steady-state knee joint torque.

Results: The results showed that the maximum voluntary torque (MVT) of the knee joint increased with the vibration frequencies. On average, the MVTs were 756.47 Nm for 0 Hz (no vibration) and 809.61 Nm for 90 Hz. There was a significant positive correlation ($r = 0.71$) between the MVTs and integrated electromyograms (iEMGs). Further, the co-contraction indices (CCIs) were computed, which represent the ratio of the iEMGs of the antagonist muscle to the iEMGs of all involved muscles. There was a significant negative correlation ($r = 0.62$) between the CCIs and MVTs, which was accompanied by a significant positive correlation ($r = 0.69$) between the iEMGs of the vibrated muscle (RF). There was no significant correlation between the MVTs and iEMGs of the antagonist muscle.

Conclusion: The results of this study suggest that the short-term vibration on the muscle increases the level of muscle activation possibly owing to the increased Ia afferent activities, which enhances the muscle force generation capability.

Keywords: Short-term muscle vibration, Maximum isometric voluntary torque, Ia-afferent, Co-contraction

INTRODUCTION

Recently, various attempts have been made to elucidate the effects of exercise by providing vibratory stimulation to the entire body or part of the body. These vibratory stimuli artificially creates gravitational conditions for aviators in gravity-free space; thus, its original purpose was to prevent functional and morphological degradations of the skeletal system. Studies have shown that vibratory stimulations might have a positive effect on the respiratory, circulatory, nervous, and endocrine systems as well as on the muscle and skeletal systems (Cardinale & Bosco, 2003; Oh, Kang, Min, & Kwon, 2015; Woo & Park, 2015); since then, such stimulations have been expanded to include fields, such as physical therapy and rehabilitation (Remaud, Cornu, & Guével, 2009). There are two general methods of vibratory stimulation; whole body vibratory stimulation and local muscle vibratory stimulation. Studies on

the whole body vibratory stimulation have been actively conducted; conversely, those on the effects of focal muscle vibratory stimulation on the skeletal muscle tissues are limited.

The effects of vibratory stimuli revealed through experimental results include both positive and negative aspects. Issurin, Liebermann, and Tenenbaum (1994) reported that vibratory stimulation training results in a significant increase in isotonic maximal muscle force and flexibility. In addition, a study conducted by Barthélémy (2016) reported that the stimulation by an 80-Hz frequency stimulated the muscle sensory afferent nerves of patients with incomplete spinal cord injuries and that vibration stimulation training improved the patients' ability to gait pattern.

Humphries, Warman, Purton, Doyle, and Dugan (2004) confirmed the effect of vibratory stimulation on muscle activation and the ratio of force progression during maximum isometric contraction; however, the results

showed that the vibratory stimulation at 50-Hz level did not significantly increase the isometric contraction force. Ekblom and Thorstensson (2011) reported that the force and muscle activity and H-reflex response did not show any significant difference after long-term vibration stimulation for more than 30 min. In addition, Rothmuller and Cafarelli (1995) reported that the effect of vibratory stimulation on the co-contraction of the antagonist muscles during fatigue progression was rather lower than that of its force.

The opposite effect of such a vibratory stimulus can be interpreted to be a result of the response characteristic of a muscle spindle, which senses a vibratory stimulus. The human body recognizes the vibration through the muscles and the tendon and shows adaptive responses to buffer the vibration. This leads to reflexive muscle contractions called tonic vibration reflexes, which improve the muscle nervous system function (Cardinale & Bosco, 2003). The frequency, amplitude, and magnitude of the vibratory stimulus are important factors in determining the effect of the vibration stimulus (Torvinen et al., 2002). The primary afferent nerves of the muscle spindles are sensitive to minute changes in muscle length; the sensitivity of the spikes increases, especially when a high-frequency vibration stimulus is applied. The primary afferent nerve of the spikes can be fired; it can respond to all vibrations at high frequencies (100 Hz), especially when a low amplitude of ~1 mm is applied to the skin or tendon (Latash, 2008). When the vibration is appropriately adjusted to the external stimulus to the muscles and provided in a way that the human body can adapt, it can lead to positive effects on the body systems, such as the muscular system, skeletal system, and immune system morphologically and functionally (Issurin et al., 1994; Issurin & Tenenbaum, 1999; Arcangel, Johnston, & Bishop, 1971; Samuelson, Jorfeldt, & Ahlborg, 1989; Warman, Humphries, & Purton, 2002). Therefore, it is important to understand the physiological characteristics of muscles and to investigate the vibration conditions (frequency and amplitude) that can yield positive effects.

Long-term vibrations have been reported to affect high-threshold motor units (Ushiyama, Masani, Kouzaki, Kanehisa, & Fukunaga, 2005) and cause illusion effects. Therefore, it is concluded that long-term vibratory stimulations have no positive effect on muscle activity and force value; hence, in this study, we investigated the positive changes in the maximum muscle strength through short-term vibrations, while considering the negative factors of long-term vibration stimulations proposed by previous studies. In addition, although previous studies have shown a consensus that the effect on the muscles varies in accordance with the frequency difference, a previous study, which did not show any significant effect of muscle vibrations during isometric contraction, was performed under a single vibratory condition of 50 Hz.

Therefore, we examined the effect of vibratory stimulation of various frequencies on the muscles under isometric contraction conditions. In this study, we also attempted to verify the following hypotheses. Hypothesis 1: There will be a difference in magnitude of maximum knee joint torque according to the change in the short-term muscle vibration frequency. Hypothesis 2: There will be a difference in the co-contraction index (CCI) between the agonist and antagonist muscles depending on the short-term muscle vibration frequency.

METHODS

1. Participants

This study was conducted on six healthy male adults in their 20 s and 30 s (age: 29.83 ± 4.21 y; height: 172.5 ± 4.5 cm; weight: 75.83 ± 12.84 kg; anterior thigh fat thickness: 3.1 ± 0.9 mm). The subjects who had no history of surgical operation of the knee joint or muscles, no dysfunction of the organs related to posture control or skin texture, and no damage or dysfunction (manual muscle testing: MMT, grade 5) in other parts of the body were selected. The body mass index of the participants was in the normal range ($18.5 \sim 23$ kg/m²). All participants were informed about the overall experimental procedure before the experiment; after completing the experiment participation agreement reviewed by the Institutional Review Board, the experiment was then conducted (IRB No. 1704/001-009).

2. Apparatus

The vibrator used in this study adjusted the frequency, amplitude, and vibration time as a form attached to the skin. Its dimensions were 1.17" in diameter and 0.30" in thickness. The each frequency, amplitude, and vibration time was controlled using a program connected with a vibrator.

A six-component force and torque sensor (AMTI MC3A, USA) was used to measure the maximum voluntary torque (MVT) of the knee joint. The sensor consists of six channels and simultaneously measures the force and moment components of the x-, y-, and z-axis, and the crosstalk was less than 2% for all channels. The force sensor was firmly fixed to the customized steel frame; for experimental purposes, it was designed to be placed between the knee and ankle joints of each subject.

In addition, the attachment position of the force sensor was adjusted according to the shank anatomy of each subject. The iron frame was fixed by setting the knee angle of the participants to 120° (Lindahl, Movin, & Ringqvist, 1969). The attached sensor was fixed to the frame after the long axis of the iron frame and the Fz component of the sensor were positioned perpendicular to each other (Figure 1). The sampling frequency of the force/torque data was set to 1,000 Hz.

A surface EMG (Trigno wireless EMG systems, Delesys, USA) was used to measure the activity of the muscles concerned with the experiment. The electrodes were attached to all four muscles, including the muscles used as the agonist muscles at the time of the extension torque of the knee joint, such as the vastus lateralis (VL), rectus femoris (RF), vastus medialis (VM), and a muscle used as an antagonist muscle, the biceps femoris (BF). Data were collected by setting the sampling frequency of the EMG to 2,000 Hz. All equipment were synchronized to start at the same time, and the experiment was conducted. All measured analog signals were digitalized via an analog-to-digital converter (AMTI, Gen5, USA) and transferred to a computer. Data were collected using the LabVIEW (National Instruments, Austin, TX) software.

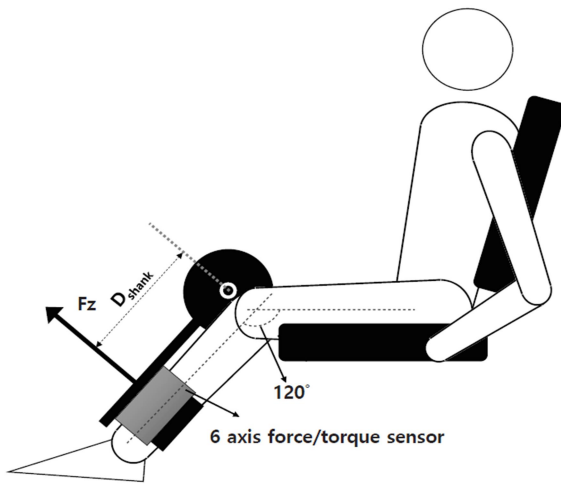


Figure 1. Experimental setting for the maximal isometric voluntary torque task. A six-axis force/torque sensor is fixed to the leg extension machine, providing feedback through the monitor in front. The iron frame is fixed by setting the knee angle of the participant at 120° , and the orientation of the attached sensor is fixed to the frame along the long axis of the iron frame. The F_z component of the sensor is perpendicular.

3. Procedure

Before starting this experiment, all participants performed full body stretching to prevent knee and thigh injuries. As a preliminary exercise step, the blood flow of the thigh muscles (quadriceps femoris and hamstring) was pre-increased using a leg-extension and leg-curl machine. In addition, exercise specialist evaluated the joint range of motion, stability, and strength of the muscles to be used in the experimental task through MMT (manual muscle test) (Daniels & Worthingham, 1986). The experiments were then conducted on those with Grade 5 levels, i.e., participants with complete range of motion for gravity and strong resistance. Before the experiment, all participants visited the laboratory to practice the maximum voluntary torque task under the no-vibration condition to become familiar with the experimental conditions. The surface electrode attached to the skin for measuring the muscle activity was located at the midpoint between the muscle insertion and the nerve distribution area along the longitudinal axis of the muscle based on the manual of a previous study (Basmajian & De Luca, 1985). In addition, the hair was removed from the attachment area of the thigh muscles to reduce the impedance generated from the skin before attaching the electrodes, and the oil was removed using cotton soaked in alcohol.

1) Vibration effect on the EMG signal

Preliminary experiments were performed prior to this experiment. The purpose of the preliminary experiment was to confirm the interference of the EMG signal by the vibration signal and to provide a method for eliminating the interference signal of the vibration included in the EMG signal.

Therefore, the interference was measured and compared at more frequencies than the frequency condition set in this experiment. First, the electrodes were attached to the same area as the measured muscle area in the present experiment, and seven frequency conditions were measured from the no-vibration condition to 30 Hz, 50 Hz, 60 Hz, 90 Hz, 110 Hz, and 140 Hz. Second, the experimental data were compared with those of the no-vibration condition at 30 Hz, 50 Hz, 60 Hz, 90 Hz, 110 Hz, and 140 Hz in a steady-state at 100 Nm of knee extension torque. A notch filter corresponding to each vibration condition was applied to remove the component of the frequency band set by the vibrator included in the EMG signal. The mean power frequency (MPF), median power frequency, power spectrum density (PSD), and integrated EMG (iEMG) values of the raw data and the notch filter applied data were compared and evaluated. As a result of the analysis, we could not observe differences between the raw data and the notch filter applied data. Therefore, we concluded that the artifact of the vibrator can be removed from the raw data through the notch filter.

2) MVT task of the knee joint

The measurement postures of all the participants were stretched to the equipment consisting of a steel frame for the knee extension motion; the waist was pulled all the way to the end; and the waist and shank of the participants were fixed using Velcro (Figure 2). Four vibrators were attached along the periphery of rectus femoris, which was the most superficial located in the anterior part (muscle belly) of the agonist muscles involved in the knee extension (Figure 2A).

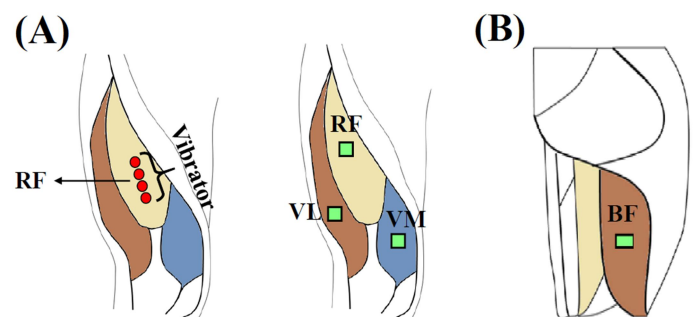


Figure 2. (A) The vibrator is attached to the rectus femoris (RF). (B) The surface electrodes are attached to the vastus lateralis (VL), RF, vastus medialis (VM), and biceps femoris (BF) to obtain EMG data from the muscles.

To obtain muscle activity data, the surface electrodes were attached to four muscles (agonist: vastus lateralis (VL), rectus femoris (RF), vastus medialis (VM), antagonist: biceps femoris (BF)) as shown in (Figure 2B). The vibratory conditions consisted of four different frequencies (0 Hz [no vibration], 30 Hz, 60 Hz, and 90 Hz) and the amplitude was provided constantly at 10 mm regardless of the four frequencies, considering the skinfold of anterior thigh to the extent that the effect of the vibration affects the muscle spindles. Four vibratory conditions

were provided randomly to exclude the learning effect. All trials were measured twice for each vibratory condition, and the average value was used for the analysis. This task was divided into two phases. The first phase is a pre-activation period that maintains the 100-Nm knee extension torque as constant as possible for 6 s. The second phase is the maximum voluntary torque period after the 6-s pre-activation phase and was instructed to generate the maximum voluntary torque within 9 seconds according to the start signal provided by the monitor. Short-term muscle vibrations were then provided from 5 s to 9 s for 4 s, 1 s before the start of the maximum voluntary torque (after 6 s) (Figure 3). During this task, all participants were monitored to obtain data on the force value at the pre-activation phase and the starting point of the maximum voluntary torque task and to rule out the perceived influence of the task performance. The visual information on the peak force was not provided.

The resulting knee extension torque values were provided as graphical visual feedback via a computer screen. To eliminate the residual effect of the vibration, a 2-3-min break time between each trial was provided, and additional breaks were also provided depending on the needs of the participants.

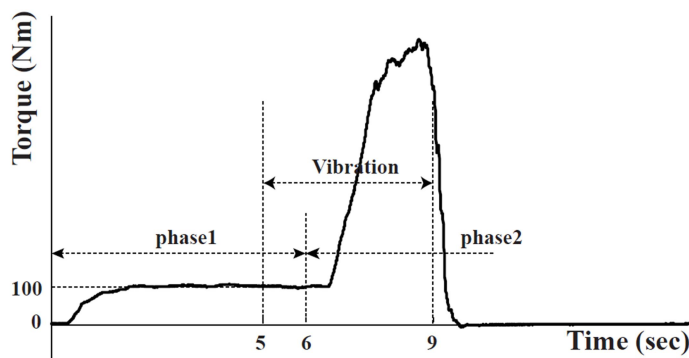


Figure 3. Sample of maximal voluntary torque task data. Phase 1 is the pre-activation period. Phase 2 is the maximum knee extension torque generation period. Muscle vibration is applied for a total of 4 s from 5 s to 9 s.

4. Data processing

All measured data were analyzed using MATLAB 14.0 (MathWorks Inc. Natick, MA, USA). The force values measured from the six-axis force/torque sensor were filtered using a zero-lag 4th-order low-pass Butterworth filter (cutoff at 10 Hz).

The processing of the EMG data for data analysis was as follows: 1) application of the notch filter to eliminate the 60-Hz noise generated by the external electronic devices, 2) application of a second notch filter to remove noise in the same frequency band as the vibrator stimulus, 3) application of 10-450-Hz bandpass filter, 4) rectification process, and 5) application of a 100-ms window moving average filter. The variable of in this study were as follows.

1) MPF when performing the MVT task

The MPF was analyzed to determine the effect on fatigue because the muscle fatigue that occurs in the MVT task of this study may affect the results. Each participant performed a total of eight MVT tasks (two per frequency), and the MPF of the agonist and antagonist muscles in each attempt was recorded.

$$MPF_i = \frac{\sum_{j=1}^n f_j \cdot P_j}{\sum_{j=1}^n f_j} \quad (\text{Equation 1})$$

i represents the number of the corresponding attempt (eight times); p represents the power spectral density (PSD); and n represents the number of samples of the PSD.

2) MVT of the knee extension

For the data analysis, the length of the point perpendicular to the center of the force sensor (D_{shank} of Equation 2) was measured from the lateral epicondyle of the femur of each participant. Using the F_z value obtained from the force sensor, the mechanical knee joint torque (KJT) was calculated using Equation 2. The MVT was defined as the maximum value in the second phase (6~15 s) of the continuous KJT values arranged with a time interval of 15 s.

$$KJT(t) = F_z(t) \cdot D_{shank} \quad (\text{Equation 2})$$

3) iEMG

The iEMG of all muscles was calculated from the point at which the torque value of the knee extension increased (onset) from the pre-activation interval to the point at which the maximum voluntary torque value was observed (peak). The onset at which the knee extension torque value begins to increase was defined as the point at which the maximum change rate of the F_z value measured from the force sensor (df_z/dt) is 5% after the pre-activation period (6~15 s) (Kim, Shim, Zatsiorsky, & Latash, 2006). Since the time window lengths of the peak and onset points were different for each experimental participant and experimental conditions, the time between the onset and the peak time extracted for each trial was resampled to 100 data, and the iEMG value was calculated using Equation 3.

$$iEMG_j = \int_1^{100} EMG_j(t) \cdot dt \quad \text{where } j = \{VL, RF, VM, BF\} \quad (\text{Equation 3})$$

4) CCI

To quantify the degree of the antagonist activity on the degree of total muscle activity, the CCI was calculated using the iEMG values of the four muscles calculated above (Equation 4).

$$CI = \frac{2 \cdot iEMG_{BF}}{(iEMG_{VL} + iEMG_{RF} + iEMG_{VM} + iEMG_{BF})} \times 100\%$$

(Equation 4)

5. Statistical analysis

The statistical analysis was performed using SPSS 24.0 (IBM, USA). The effect of the task trial (level 8) factor on the MPF was confirmed using one-way repeated measures analysis of variance (ANOVA). The effects of the frequency factors (four levels: 0, 30, 60, and 90 Hz) on the MVT and CCI were also verified using the one-way repeated measures ANOVA, and a paired *t*-test was used to confirm the difference of the one-to-one correspondence of the frequency conditions. A linear regression analysis was performed to analyze the change in the iEMG of the agonist muscles which was including the muscles provided with the vibratory stimulation, and antagonist muscle, according to the MVT changes. The significance level of all statistical analyses was set at $\alpha = 0.05$.

RESULTS

1. MPF when performing the MVT task

The MPF of the measured agonist (VM, RF, VL) and antagonist (BF) muscles EMG signals during the MVT task was found to be unchanged during a total of eight MVT tasks. These results were confirmed using the one-way repeated measures ANOVA, where the task trial (level 8) factor was set as a factor and the MPF as a dependent variable. The main effect of the task trial factor was not statistically significant (Figure 4).

2. MVT of the knee joint

In this study, the MVT value according to the frequency change of the muscle vibration was analyzed.

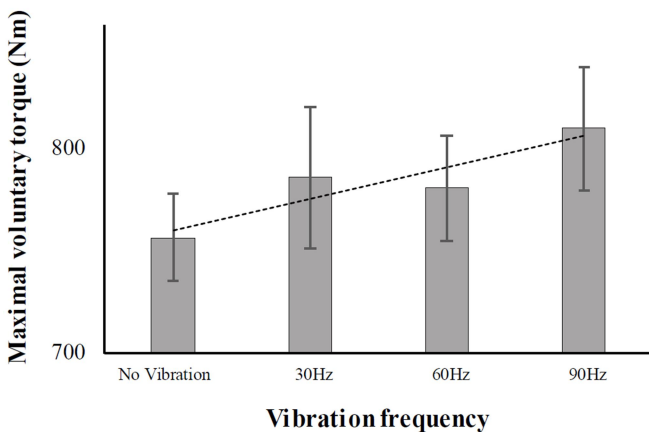


Figure 4. Maximum voluntary torque of the knee joints of the six participants according to the vibration frequency. The average and standard errors of the six participants are shown.

The results showed that the MVT of the knee joint increased with the vibration frequencies as compared to 0 Hz (no-vibration) (Figure 4). On average, the MVTs were 756.47 Nm for 0 Hz (no vibration), 785.74 Nm for 30 Hz, 780.61 Nm for 60 Hz, and 809.61 Nm for 90 Hz. These results were confirmed using the one-way repeated measures ANOVA. The main effect of the frequency factor (4th level: 0, 30, 60, and 90 Hz) was statistically significant ($F_{[3, 15]} = 3.89, p < 0.05$), and a statistically significant difference ($P < 0.05$) was found between the MVT of 0 Hz and 30 Hz <MVT of 90 Hz using the post hoc paired *t*-test.

3. CCI

The CCI indicates the degree of activity of the antagonist muscle relative to the measured total muscle activity. The CCI tended to decrease with increasing frequency as compared to 0 Hz (no-vibration) (Figure 5A). These results were confirmed using the one-way repeated measures ANOVA, and the main effects on the frequency factors (four levels: 0, 30, 60, and 90 Hz) were statistically significant ($F_{[3, 15]} = 3.48, p < 0.05$). In addition, the relationship between the MVT and CCI in all

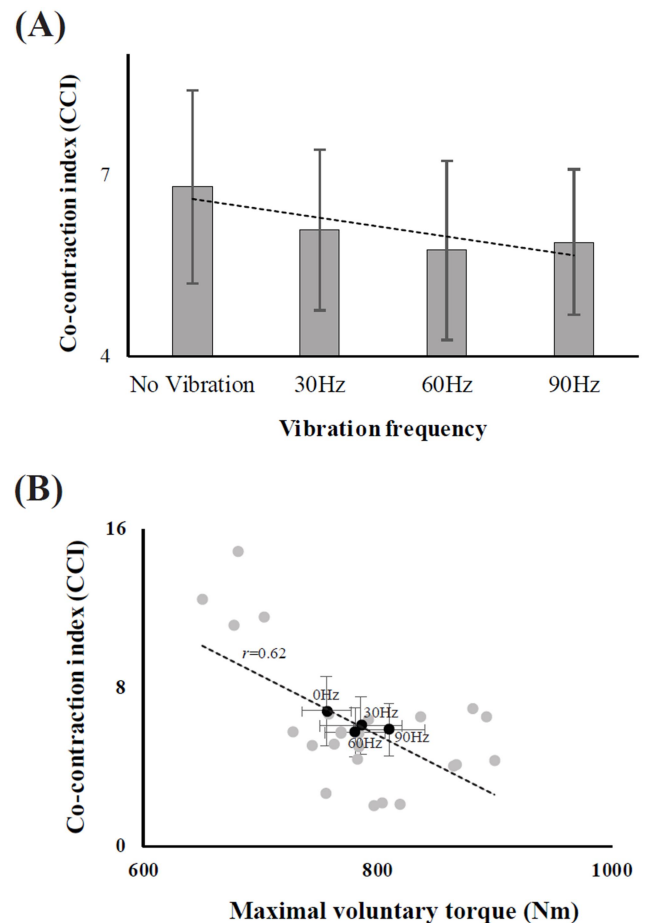


Figure 5. (A) Average and standard error of the co-contraction index (CCI) of the six participants according to the vibration frequency. (B) Scatter plot and correlation coefficient of the maximal voluntary torque and CCI. The gray dots represent individual data, and the black dots represent the average and standard error of the participants in each frequency condition.

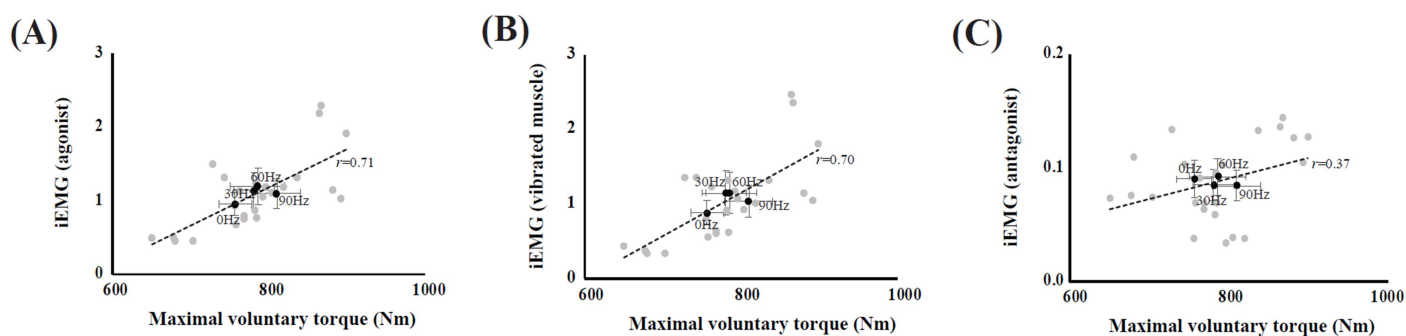


Figure 6. Scatter plot of the maximal voluntary torque values and (A) the agonist, (B) the muscle provided with the vibration stimulus, and (C) the antagonist integral electromyogram (iEMG) value. The gray dots represent individual data, and the black dots represent the average and standard error of the participants in each frequency condition.

participants and experimental conditions showed a negative correlation ($r = 0.62$). The dark points in (Figure 5B) show the average value of the participants in each frequency condition, and it can be confirmed that the slope of the linear function connecting the average points is also a negative value. Therefore, the increase in the MVT by to the muscle vibration was related to the decrease in the CCI.

4. iEMG vs MVT

(Figure 6) shows that results of relationship between iEMG of the vibrated muscle (RF), agonist muscles (VM, RF, VL), and antagonist muscle (BF). According to the results of the current study, all values, including the iEMG values of the agonist muscle ($r = 0.71$, Figure 6A), vibrated muscle ($r = 0.70$, Figure 6B), and antagonist ($r = 0.37$, Figure 6C), tended to increase with increasing MVT. The black dots shown in (Figure 6) represent the mean values of the participants in each frequency condition, and the slope of the linear function shows a positive value. In addition, the slope of the linear function of the agonist muscle (0.0052) and the muscle vibrated muscle (0.0058) was relatively larger than the linear function slope of the antagonist muscle (0.0002).

DISCUSSION

This study examined the positive changes that can be attributed to the maximum muscle strength through stimulation of various frequencies applied to the muscles. The results of this study confirmed that the increase in the MVT due to a short-term muscle vibratory stimulation (Hypothesis 1), and the muscle vibratory stimulus showed a relative decrease in the co-contraction of the antagonist muscle to the degree of activity of the entire muscle (Hypothesis 2). This result can be explained by the activation of the Ia-afferent of the agonist muscles and the simultaneous contraction of the antagonist muscle, which were discussed below based on the additional results of this study.

The muscle spindles and Golgi tendon organs are mechanoreceptors of the muscle that detect length, tension, and velocity of stretch of the muscles and transmit to the central nervous system. Further, the muscle spindle is main sensory organs, which detect the change in the length of the muscle and regulate the length of the muscle by causing reflex

contractions of the muscle (Cardinale & Bosco, 2003). The Ia-afferent of the muscle spindle is reported to activate in response to high frequency vibrations (Latash, 2008), which has been known as one of the causes of increased strength (Griffin, 2012).

In previous studies, muscle vibration has been associated with high activation of various skin and subcutaneous receptors; further, it has been reported that the Ia-afferent of the agonist muscle also cause a very high level of activity (Baik & Lim, 2006; Brown et al., 1967; Cordo et al., 1998; Roll & Vedel, 1982). In the study of Sabin (2003), it was confirmed that the lower extremity muscles were activated by vibratory stimulation during gait, which was attributed to vibration activating Ia-afferent of muscle spindle.

The results of this study also showed that the MVT statistically and significantly increased after the application of short-term muscle vibration at a high frequency (90 Hz) compared with the low-frequency (30 Hz) or no-vibration condition. A previous study (Park and Martin, 1993) using vibratory stimuli of various frequencies on the finger flexor tendons showed that as the frequency increases, the tonic vibration reflexes increases, but decreases at higher frequencies above 150 Hz. In this study, the increase in the MVT with increasing frequency is consistent with the results of previous studies, and based on our results, the vibratory stimulation to the muscles within the frequency range of 100 Hz or less has a positive effect on the MVT because of the increase in the tonic vibration reflex, which affects the maximum muscle strength as the frequency increases.

Simultaneous contraction of the agonist and antagonist muscles is a strategy used to control joint stability in various movements. In a previous study, mechanical instability of the joints also increased the simultaneous contraction of the agonist and antagonist muscles (Milner, 2002). This simultaneous contraction enhances the stability of the joint; thus, it is useful in learning new tasks or in actions requiring high accuracy (Hunter, Ryan, Ortega, & Enoka, 2002). In fact, the ability to control the simultaneous contraction of the muscles around the joint to minimize external perturbation is important to improve the effectiveness of certain exercise tasks (Hasan, 1986).

In this study, we investigated the relative changes in the CCI according to the frequency difference in the MVT task. Our data showed that the CCI of the agonist and antagonist muscles decreased with increasing

MVT and frequency. The MVT of the knee joint significantly increased as the frequency of the short-term muscle vibration increased, and as a result of the analysis of the muscle activity through iEMG, the muscle activity increased linearly with increasing MVT. In addition, the activity of the agonist and antagonist muscles tended to increase with increasing MVT as the frequency of the short-term muscle vibrations increased; however, the activities of the agonist muscles tended to increase more than those of the antagonist muscles. The difference in muscle activity between the agonist and antagonist muscles seems to result in a relative decrease in the CCI despite the tendency to increase both the activity of the agonist muscles and the antagonist muscle. Previous studies reported that contraction of the antagonist muscle decreased the effect of torque generated by the agonist muscle; thus, it was necessary to reduce the simultaneous contraction to maximize the force exerted by the agonist muscle (Ford, Van den Bogert, Myer, Shapiro, & Hewett, 2008).

In conclusion, the reduction in the CCI in this study seems to also reduce the simultaneous contraction of the antagonist muscle as reported in previous studies to produce a high level of MVT during the task. Further, these results suggest that short-term vibration stimulations applied to the muscle spindle activate the Ia-afferent nerve of the muscles and allow Ia reciprocal inhibition through the Ia inhibitory interneurons (Crone, Hultborn, Jespersen, & Nielsen, 1987).

The results of this study were as follows. First, according to short-term muscle vibratory frequencies, there is a difference in the KJT during isometric knee extension exercises. Second, the hypothesis that there is a difference in the CCI between the agonist muscle and the antagonist muscle according to the short-term muscle vibration frequency was tested. Both hypotheses were verified through the results of the study.

In the current study, we investigated how the role of the muscles that generate torque required for movement changes with external stimuli. However, although the muscles play the role of a torque generator in the human movement system, how the muscles involved in movements actually coordinate is an important factor in determining the characteristics of various human movements. A previous study (Arpinar-Avsar, Park, Zatsiorsky, & Latash, 2013) that examined the changes in intramuscular coordination by vibration stimuli in multi-finger movements showed that during the task of generating force using the finger, the vibration stimulus caused a change in coordination between the elements included in the movement. Therefore, based on these previous studies, further investigation of the effects of short-term vibratory stimulation on the coordination pattern of the muscles to perform a specific task will enable a deeper understanding of the human movement system in response to external stimuli.

CONCLUSION

The purpose of this study was to investigate the effects of short-term muscle vibration on muscular strength. To investigate such effects, the subjects were asked to perform the MVT tasks with no-vibration, 30 Hz, 60 Hz, and 90 Hz (amplitude: 10 mm). Further, the MVT of the knee joint and the muscle activity of the agonist and antagonist muscles

were measured. As a result, the CCI decreased as the frequency of the short-term muscle vibration increased. A larger MVT was produced when short-term muscle vibrations of high frequency (90 Hz) were provided than when those of a low frequency (30 Hz) or no-vibration was provided. These results will provide a basis for understanding the response of the muscles to external vibration stimuli and understanding the mechanisms of motor control. Furthermore, the muscle vibration will be used as an external stimulus to cause a positive response of the muscles, thereby contributing to the prevention and rehabilitation of injuries and improvement of athletic performance via its application as an auxiliary device.

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